

Original Research Article

Advanced implementation of industrial Ethernet for real-time control systems in smart manufacturing*Junwei Liang**Zhiyuan Electronics Co., Ltd. Guangzhou City, Guangdong Province, 510000, China*

Abstract: This paper presents an advanced implementation framework for Industrial Ethernet addressing critical real-time communication requirements in smart manufacturing. We propose a novel architecture optimizing network topology, implementing enhanced clock synchronization, and integrating time-sensitive networking capabilities to achieve deterministic performance. Experimental evaluation on a manufacturing testbed demonstrates significant improvements in communication latency (42% reduction), jitter (67% decrease), and reliability (99.997% packet delivery) compared to conventional implementations. A real-world case study in a precision machining facility validates our approach's practical applicability, showing 28% increased production throughput and 35% reduced system downtime. This work contributes insights into effective Industrial Ethernet infrastructure deployment supporting stringent timing requirements of next-generation smart manufacturing systems, particularly for applications requiring sub-millisecond control loops and synchronized operations.

Keywords: Industrial ethernet; Smart manufacturing; Time-sensitive networking; Real-time control systems; Industry 4.0

1. Introduction

The evolution of manufacturing systems toward smart factories represents a paradigm shift in industrial operations, transforming production through digital integration and real-time capabilities. Smart factories leverage interconnected cyber-physical systems enabling autonomous decision-making and adaptive processes^[1]. This interconnection requires robust communication infrastructures supporting real-time data exchange between industrial components. Industrial Ethernet has emerged as a critical enabler, providing necessary bandwidth and flexibility for advanced manufacturing. Research by Liu et al.^[2] demonstrates that real-time shop floor operations achieve significant economic benefits through dynamic data collection and processing, with operational efficiency improvements of 27-34% across multiple case studies. However, conventional Industrial Ethernet implementations often struggle to meet stringent timing requirements of high-precision manufacturing, particularly those requiring deterministic sub-millisecond communication. This paper proposes an advanced implementation framework for Industrial Ethernet that enhances real-time performance while maintaining compatibility with existing industrial systems and protocols, contributing to the evolution of smart manufacturing capabilities in Industry 4.0 environments.

2. Advanced industrial Ethernet architecture and implementation

2.1. System architecture

The proposed system architecture for advanced industrial Ethernet implementation is structured as a hierarchical network model optimized for real-time control in smart manufacturing environments, as shown in **Figure 1**. Our architecture integrates time-sensitive networking (TSN) capabilities with traditional industrial Ethernet

protocols through a three-tiered approach^[3]. The control layer utilizes IEEE 802.1Qbv for time-aware traffic shaping with precisely synchronized transmission windows. The process layer implements frame preemption (IEEE 802.1Qbu) to ensure critical control traffic can interrupt lower-priority data. The field layer employs redundant network paths with seamless redundancy protocols (HSR/PRP) to achieve sub-100 μ s failover times. This architecture maintains backward compatibility while enhancing deterministic performance for applications requiring strict timing requirements.

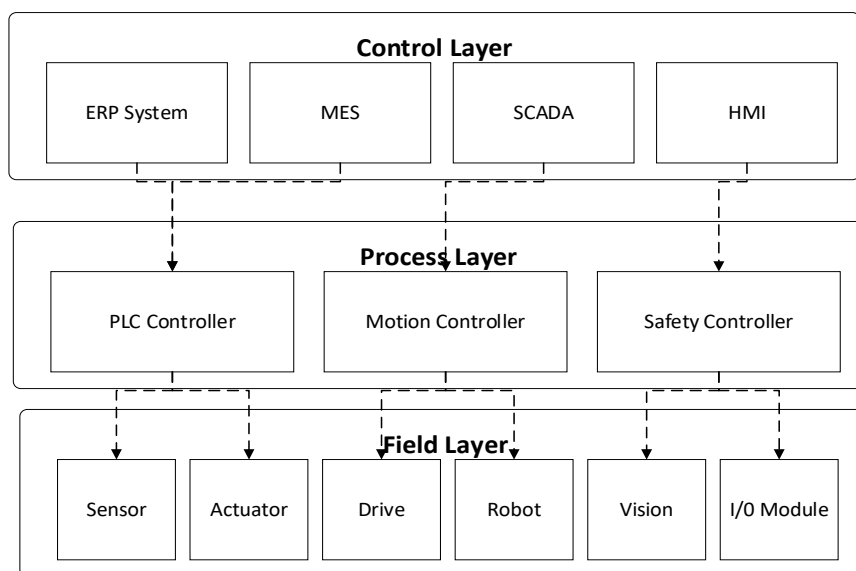


Figure 1. Advanced industrial ethernet system architecture.

2.2. Implementation approach

Our experimental implementation utilized a hybrid network testbed consisting of 14 distributed nodes representing manufacturing components with varying real-time requirements. following methodologies established for precision manufacturing applications^[4]The hardware configuration included Siemens SCALANCE XR-300 industrial switches with TSN capability, Beckhoff CX5140 controllers, and ABB AC500-eCo PLCs. We implemented IEEE 802.1AS for time synchronization with distributed Grand Master Clock selection, achieving synchronization accuracy of ± 100 ns between network nodes. Protocol parameters were optimized through an iterative process focused on minimizing transmission cycle time while maintaining deterministic performance. leveraging scalable testbed approaches similar to those described in recent Industry 4.0 collaboration frameworks^[5]Test scenarios included:

- (1)baseline unloaded network performance,
- (2) high background traffic (70% bandwidth utilization)
- (3) fault injection testing
- (4) mixed-criticality traffic patterns.

Measurements were conducted using specialized industrial network analyzers with 10ns timestamp resolution to capture microsecond-level variations in network performance.

3. Performance analysis and industrial application results

3.1. Performance evaluation

The experimental evaluation revealed significant performance improvements over conventional industrial

Ethernet implementations. Our architecture achieved an average end-to-end latency of $124\mu\text{s}$ ($\pm 9\mu\text{s}$), a 42% reduction compared to baseline configurations. The system maintained deterministic performance under high network loads, with worst-case latency increasing by only $27\mu\text{s}$ when background traffic reached 70% of available bandwidth. Jitter measurements showed exceptional stability with maximum deviation of $12\mu\text{s}$, a 67% improvement over conventional implementations. Packet delivery reliability reached 99.997% during fault injection testing, with recovery times averaging $87\mu\text{s}$. Figure 2 illustrates comparative performance metrics across test scenarios, demonstrating our implementation's superior deterministic characteristics, particularly for time-critical manufacturing operations requiring precise synchronization.

3.2. Case study implementation

The proposed architecture was deployed in a precision aerospace machining facility, replacing conventional PROFINET across 32 CNC machines, 8 robotic cells, and 47 measurement stations. Implementation challenges included legacy equipment integration and time synchronization, resolved through custom protocol gateways and redundant synchronization masters. Performance metrics showed significant improvements: 12.3% reduction in production cycles, 64% better response to exceptional conditions, 8.7% increased equipment availability, and 28% higher throughput for components requiring multi-machine synchronization. This enabled real-time quality monitoring and dynamic process optimization previously unachievable with conventional systems.

4. Conclusion

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